

C-RED New Space

New Space Applications SWIR Camera Core

Key Specifications

- ✓ SWIR 0.9 1.7 µm
- ✓ Full Frame 600 fps
- √ <30 e- read noise
 </p>
- ✓ 640 x 512 InGaAs, 15 µm pixel pitch
- ✓ High dynamic range: 93 dB & true 16 bits
- ✓ Designed for space optical payloads
- ✓ Board level for easy integration

Key Applications

- ✓ FSO communications
- ✓ Space exploration
- ✓ Data exchange
- Cubesats
- Earth observations
- Environmental monitoring
- ✓ Gas detection



Introducing C-RED New Space



C-RED New Space is a SWIR camera core specifically tailored for satellite optical payloads. Based on a VGA InGaAs sensor with a resolution of 640x512 pixels and a 15 μ m pixel pitch, the camera is sensitive in the 0.9 to 1.7 μ m range with a quantum efficiency exceeding 70% from 1000 to 1650 nm.

C-RED New Space is an off-the-shelf SWIR camera module, for a successful seamless integration into any system,

specifically satellite optical payloads. The camera offers extensive customization in hardware, electronic design and firmware to ensure optimal performance and support the demanding conditions of space operations.

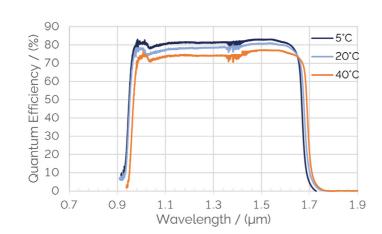
The camera offers a full frame acquisition speed of 600 frames per second and up to 32066 frames per second in 32x4 in windowing mode. Its high frame rate optimizes temporal resolution, making it invaluable for applications that involve rapid changes or movements.

This high frame rate is combined to an extreme sensitivity and high dynamic range, without compromises. C-RED New Space offers a readout noise below 30 electrons and a 93 dB and true 16 bits high dynamic range mode: it enables imaging and sensing in ultra low light conditions and various light intensities. Additionally, the camera can operate across a large operational temperature range, making it suitable for challenging environments. Its advanced thermal design ensures low and repeatable noise, as well as maintained quantum efficiency performances.

C-RED New Space is equipped with a high-throughput CameraLink® interface, ensuring minimal latency and optimal real time capability. Other interfaces can be provided upon request. The camera is designed to be customizable both on hardware and software aspects, and offers multiple assets for

an easy integration into your system: user presets and synchronization configurations, along with onboard processing features including AGC, 2-point NUC (Non Uniformity Correction), and image flip.

Contact us to discuss your project.



Technical Specifications

Some specifications are project dependent, please contact us to discuss your specific requirements.

	C-RED New Space		
	640 x 512 pixels 0.3 Mp		
	15 μm		
	14 bit		
Readout Noise at high	<30 e-		
Fla	>70%		
Operability due to signal respo	> 99.8 %		
	low gain	1.4 Me-	
Image full well capacity	medium gain	115 ke-	
	high gain	34 ke-	
	full frame	600 fps	
Frame rate	32 x 4 (min) pixels	32066 fps	
	320 x 256 pixels	1779 fps	
Power	Sensor: 0.5 W to 13.9 W max Stack: 6 W		

Additional Features	All models		
Output	CameraLink®		
Triggering	LVTTL synchronization (5 V tolerant)		
High Dynamic Range mode	93 dB and true 16 bits		
Configuration	Fast configuration switch mode (To be developed)		
Operating temperature	Dependent on mechanical integration		
Software	Graphical User Interface: First Light Vision Software Development Kit: (C, C++, C#, Python, MatLab LabVIEW / µManager)		

	Frame rate table cropping mode CameraLink® output						
	Columns						
Lines		32	64	128	256	512	640
	4	32066	31512	30458	28548	25367	24029
	8	28108	27348	25945	23532	19840	18397
	16	22542	21631	20015	17413	13819	12526
	32	16147	15254	13736	11455	8599	7646
	64	10302	9596	8440	6801	4898	4297
	128	5975	5509	4765	3752	2632	2291
	256	3247	2975	2547	1978	1367	1184
	512	1697	1549	1319	1016	697	602

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Items shipped with your camera:

1x Camera (model as ordered)

1x Power supply

1x Power supply cable

Minimum Computer Requirements:

RAM: 8 GB minimum

Processor: Intel® Core™ i5 or higher Screen resolution: at least 1920 x 1080

See system requirements for more information.

Operating and Storage Conditions

Operating Temperature: Mechanical integration dependent

Camera Part	Min Temperature/°C	Max Temperature/°C		
Sensor		60		
CPU		90		
Interface	-20	70		
Backend		70		
Ambient		65		

- Relative Humidity: 95% (non-condensing) (Cooling off or cooling on with ambient temperature above the dew point.)
- Storage Temperature: -40°C to 60°C

Power Requirements

- 100 264 VAC 50 60 Hz
- Max. power consumption: Sensor: 0.5 W to 13.9 W max Stack: 6 W

Footnotes: Specifications are subject to change without notice

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